



All Motors

MOTOR APPLICATION

Use of Engine Driven Generators - Single-Phase or Three-Phase

Table 5 lists minimum generator sizes based on typical 80 °C rise continuous duty generators, with 35% maximum voltage dip during starting, for Franklin's three-wire motors, single- or three-phase.

This is a general chart. The generator manufacturer should be consulted whenever possible, especially on larger sizes.

There are two types of generators available: externally and internally regulated. Most are externally regulated. They use an external voltage regulator that senses the output voltage. As the voltage dips at motor start-up, the regulator increases the output voltage of the generator.

Internally regulated (self-excited) generators have an extra winding in the generator stator. The extra winding senses the output current to automatically adjust the output voltage.

Generators must be sized to deliver at least 65% of the rated voltage during starting to ensure adequate starting torque. Besides sizing, generator frequency is important as the motor speed varies with the frequency (Hz). Due to pump affinity laws, a pump running at 1 to 2 Hz below motor nameplate frequency design will not meet its performance curve. Conversely, a pump running at 1 to 2 Hz above may trip overloads.

Generator Operation

Always start the generator before the motor is started and always stop the motor before the generator is shut down. The motor thrust bearing may be damaged if the generator is allowed to coast down with the motor running. This same condition occurs when the generator is allowed to run out of fuel.

Follow generator manufacturer's recommendations for de-rating at higher elevations or using natural gas.

Table 5 Engine Driven Generators

NOTE: This chart applies to 3-wire or 3-phase motors. For best starting of 2-wire motors, the minimum generator rating is 50% higher than shown.

MOTOR RATING		MINIMUM RATING OF GENERATOR			
HP	KW	EXTERNALLY REGULATED		INTERNALLY REGULATED	
		KW	KVA	KW	KVA
1/3	0.25	1.5	1.9	1.2	1.5
1/2	0.37	2	2.5	1.5	1.9
3/4	0.55	3	3.8	2	2.5
1	0.75	4	5.0	2.5	3.13
1.5	1.1	5	6.25	3	3.8
2	1.5	7.5	9.4	4	5
3	2.2	10	12.5	5	6.25
5	3.7	15	18.75	7.5	9.4
7.5	5.5	20	25.0	10	12.5
10	7.5	30	37.5	15	18.75
15	11	40	50	20	25
20	15	60	75	25	31
25	18.5	75	94	30	37.50
30	22	100	125	40	50
40	30	100	125	50	62.5
50	37	150	188	60	75
60	45	175	220	75	94
75	55	250	313	100	125
100	75	300	375	150	188
125	93	375	469	175	219
150	110	450	563	200	250
175	130	525	656	250	313
200	150	600	750	275	344

WARNING: To prevent accidental electrocution, automatic or manual transfer switches must be used any time a generator is used as standby or back up on power lines. Contact power company for use and approval.

Use of Check Valves

It is recommended that one or more check valves always be used in submersible pump installations. If the pump does not have a built-in check valve, a line check valve should be installed in the discharge line within 25 feet of the pump and below the draw down level of the water supply. For deeper settings, check valves should be installed per the manufacturer's recommendations. More than one check valve may be required, but more than the recommended number of check valves should not be used.

Swing type check valves are **not** acceptable and should never be used with submersible motors/pumps. Swing type check valves have a slower reaction time which can cause water hammer (see next page). Internal pump check valves or spring loaded check valves close quickly and help eliminate water hammer.

Check valves are used to hold pressure in the system when the pump stops. They also prevent backspin, water hammer and upthrust. Any of these can lead to early pump or motor failure.

NOTE: Only positive sealing check valves should be used in submersible installations. Although drilling the check valves or using drain-back check valves may prevent back spinning, they create upthrust and water hammer problems.

A. Backspin - With no check valve or a failed check valve, the water in the drop pipe and the water in the system can flow down the discharge pipe when the motor

stops. This can cause the pump to rotate in a reverse direction. If the motor is started while it is backspinning, an excessive force is placed across the pump-motor assembly that can cause impeller damage, motor or pump shaft breakage, excessive bearing wear, etc.

- B. Upthrust** - With no check valve, a leaking check valve, or drilled check valve, the unit starts under a zero head condition. This causes an uplifting or upthrust on the impeller-shaft assembly in the pump. This upward movement carries across the pump-motor coupling and creates an upthrust condition in the motor. Repeated upthrust can cause premature failure of both the pump and the motor.
- C. Water Hammer** - If the lowest check valve is more than 30 feet above the standing (lowest static) water level, or a lower check valve leaks and the check valve above holds, a vacuum is created in the discharge piping. On the next pump start, water moving at very high velocity fills the void and strikes the closed check valve and the stationary water in the pipe above it, causing a hydraulic shock. This shock can split pipes, break joints and damage the pump and/or motor. Water hammer can often be heard or felt. When discovered, the system should be shut down and the pump installer contacted to correct the problem.



All Motors

MOTOR APPLICATION

Wells – Large Diameter, Uncased, Top Feeding, and Screened Sections

Franklin Electric submersible motors are designed to operate with a cooling flow of water over and around the full length of the motor.

If the pump installation does not provide the minimum flow shown in Table 6, a flow inducer sleeve (flow sleeve) must be used. The conditions requiring a flow sleeve are:

- Well diameter is too large to meet Table 6 flow requirements
- Pump is in an open body of water
- Pump is in a rock well or below the well casing
- The well is “top-feeding” (a.k.a. cascading)
- Pump is set in or below screens or perforations

Water Temperature and Flow

Franklin Electric’s standard submersible motors, except Hi-Temp designs (see note below), are designed to operate up to maximum service factor horsepower in water up to 86 °F (30 °C). A flow of 0.25 ft/s for 4” motors rated 3 hp and higher, and 0.5 ft/s for 6” and 8” motors is required for proper cooling. Table 6 shows minimum flow rates, in gpm, for various well diameters and motor sizes.

If a standard motor is operated in water over 86 °F (30 °C), water flow past the motor must be increased to maintain safe motor operating temperatures. See HOT WATER APPLICATIONS on page 7.

NOTE: Franklin Electric offers a line of Hi-Temp motors designed to operate in water at higher temperatures or lower flow conditions. Consult factory for details.

Table 6 Required Cooling Flow

MINIMUM GPM REQUIRED FOR MOTOR COOLING IN WATER UP TO 86 °F (30 °C)			
CASING OR SLEEVE ID INCHES (MM)	4” MOTOR (3-10 HP) 0.25 FT/S GPM (L/M)	6” MOTOR 0.50 FT/S GPM (L/M)	8” MOTOR 0.50 FT/S GPM (L/M)
4 (102)	1.2 (4.5)	-	-
5 (127)	7 (26.5)	-	-
6 (152)	13 (49)	9 (34)	-
7 (178)	20 (76)	25 (95)	-
8 (203)	30 (114)	45 (170)	10 (40)
10 (254)	50 (189)	90 (340)	55 (210)
12 (305)	80 (305)	140 (530)	110 (420)
14 (356)	110 (416)	200 (760)	170 (645)
16 (406)	150 (568)	280 (1060)	245 (930)

0.25 ft/s = 7.62 cm/sec 0.50 ft/s = 15.24 cm/sec

1 inch = 2.54 cm

Flow Inducer Sleeve

If the flow rate is less than specified, then a flow inducer sleeve must be used. A flow sleeve is always required in an open body of water. FIG. 1 shows a typical flow inducer sleeve construction.

EXAMPLE: A 6” motor and pump that delivers 60 gpm will be installed in a 10” well.

From Table 6, 90 gpm would be required to maintain proper cooling. In this case adding an 8” or smaller flow sleeve provides the required cooling.

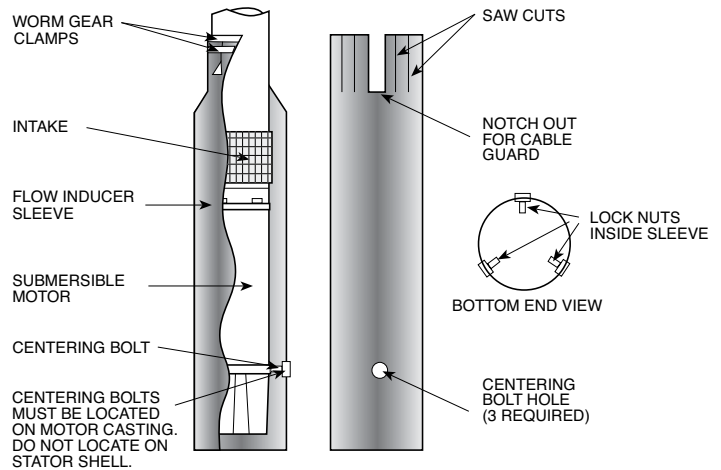


FIG. 1